

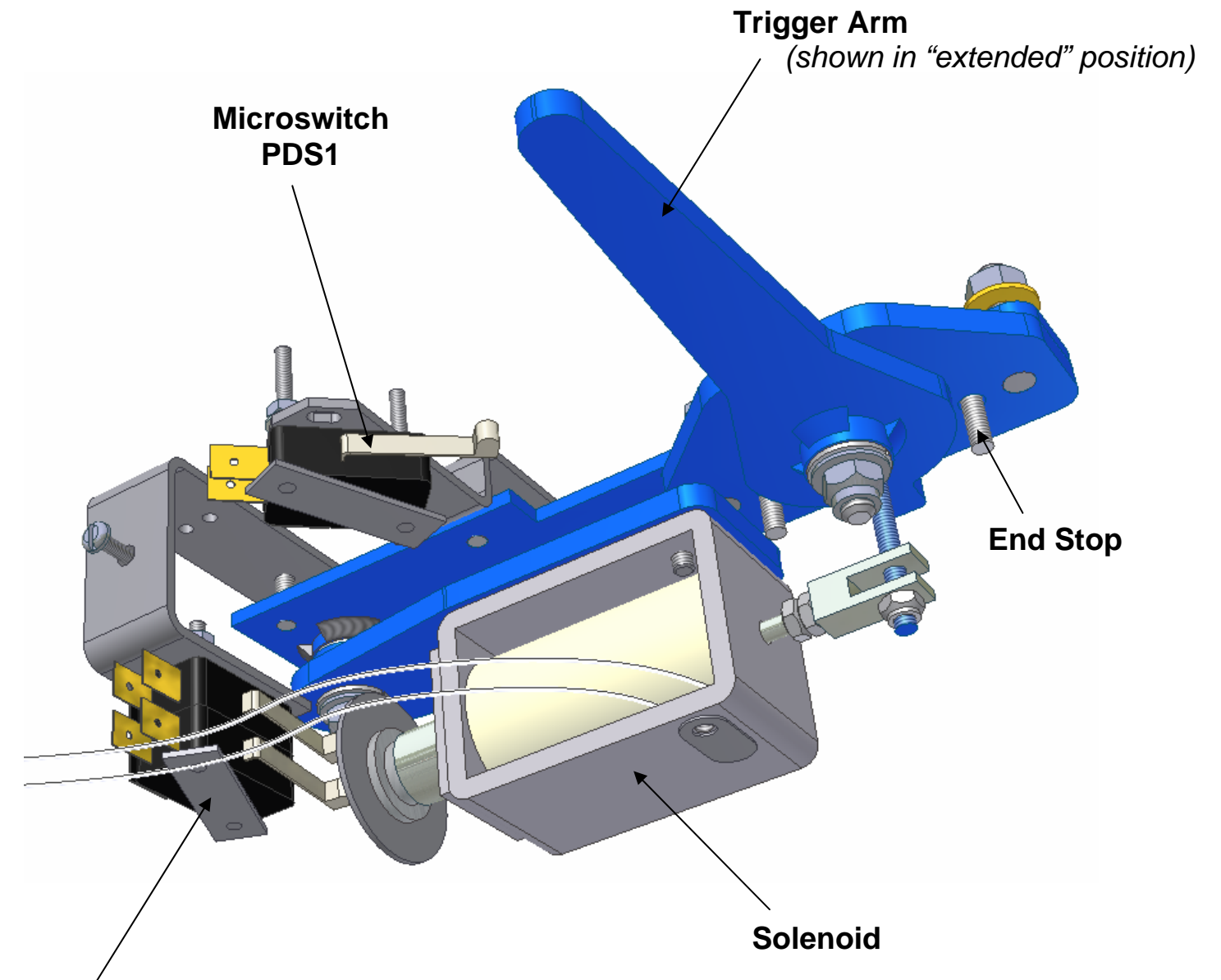


## Pawl Device Fault Finding Guide

This guide is to assist in fault finding MRLi lifts that are equipped with the Pawl Device. Potential reliability issues associated with the pawl device would fall in to one of the following 4 categories:

1. Lift fails to run (*resulting in a JTT fault*)
2. Safety gear triggered by pawl device (*resulting in an SCF fault*)
3. Lift has run upwards with the pawl device not in its retracted position (*resulting in clash with activation plate and likely damage to pawl device, plate and or safety gear arm*)
4. Doors fail to open

When the fault is intermittent, tests 1 to 4 (detailed in the pawl device installation guide) must be carried out to verify that the device is correctly wired and functioning as intended BEFORE moving on to the fault finding table overleaf.



**Microswitches  
PDS2 & PDS3**

*(identified by wiring terminations, see below)*

*PDS2 = wire 4 and 'link wire'*

*PDS3 = wire 5 and wire 6*

**Intermittent Faults:** If the lift has experienced a fault but now seems to be functioning correctly, please perform Tests 1 to 4 detailed in the “Pawl Device Installation Guide” to verify that the pawl device circuitry is connected correctly and functioning as intended BEFORE referring to the fault finding table below.

Ref. No.	Symptom	Fault	Checks/measurements	Possible Cause	Corrective Action	Reference material
1	<p><b>Lift fails to run down OR Lift fails to run up (motor running)</b></p> <p>This could be during normal running and/or relevelling.</p> <p>Nexus will display “Lift running down” or “Lift running up” and will then log a JTE fault followed by a JTT fault. There may also be releve timeouts logged.</p>	<p>VD (“VMD”) and/or VS (“VMP”) signal(s) missing</p>	<p>Place a call and then see if VD or VS inputs are present, either by viewing GEV inputs in menu 1-6 of the hand held programmer OR measure voltage between COM &amp; VMD or COM &amp; VMP: should measure approx 20 to 24Vdc.</p> <p>If the fault appears to be intermittent the above checks may not show a problem.</p> <p>Viewing the lift events prior to the JTE fault will provide you with the floor position and direction of travel that the failure occurred. This may help to determine whether VD, VS or both signals have been missing.</p> <p><i>Refer to ‘GEV booklet’ for details of menu 1-6.</i> <i>Refer to ‘Nexus Reference Manual’ for details of how to view details in the event log.</i></p>	PDS1 microswitch - incorrectly positioned	Adjust to correct position	Refer to ‘Pawl Device Installation Guide’
				PDS1 microswitch - inconsistent operation (due to insufficient solenoid stroke)	Trigger arm should reach the physical end stop. If it does not, adjust the solenoid stroke and re-adjust PDS1 as per the Installation Guide.	Refer to ‘Pawl Device Installation Guide’
				PDS1 microswitch - inconsistent operation (due to mechanical binding of the trigger arm assembly etc)	<p>Check for full and free operation of the pawl device assembly (by manually pushing and releasing at the disc on the rear of the solenoid). If the assembly binds or is stiff in operation check the following areas:</p> <ul style="list-style-type: none"> <li>- solenoid plate pivot (<i>permitted to slacken nyloc nut up to a max of 1/2 turn from it’s fully tightened position</i>)</li> <li>- trigger arm pivot (<i>permitted to slacken nyloc nut up to a max of 1/2 turn from it’s fully tightened position</i>)</li> <li>- M4 nyloc solenoid support nut (check that it has not been wound too far up or down the stud)</li> </ul>	Refer to ‘Pawl Device Installation Guide’ and make adjustments as described.
				PDS1 microswitch - inconsistent operation (due to microswitch lever arm having been bent to fit)	<p>The microswitch lever must be straight. If the arm can be straightened satisfactorily (i.e. it was only slightly bent) then do so. Adjust PDS1 switch position - if insufficient adjustment is available it is likely that the switch/bracket/mounting plate are incorrectly assembled. See Installation Guide.</p> <p>If the arm was bent a considerable amount it will be necessary to replace the microswitch.</p>	<p>Refer to ‘Pawl Device Installation Guide’</p> <p>Replacement part no. 908077</p>
				PDS1 microswitch - loose electrical connection	Check the wiring connections to PDS1 (wire 3, link wire and wire 4)	Refer to wiring diagram 9333/730 and schematic 1009238 (9333/750 & 1009239 if 2 car entrances)
				PDS1 microswitch - damaged or faulty	<p>Check for visual signs of damage (e.g. broken casing, excessive play in actuating lever, loose spade terminals etc)</p> <p>Replace PDS1 if external damage can be seen and/or the operation of the switch feels abnormal.</p>	Replacement part no. 908077
				Solenoid failing to energise	<p>Check solenoid connections (wires 1 and 2)</p> <p>Check voltage between COM and PDA. Should not be less than 9Vdc. If this voltage is less than 9Vdc OR the lift appears to fail to run in the down direction only, carry out modification to the GEV pcb supply (see TB96)</p>	<p>Refer to wiring diagram 9333/730 and schematic 1009238 (9333/750 &amp; 1009239 if 2 car entrances)</p> <p>Refer to technical bulletin TB96</p>
				PDR relay not energising	<p>Check all connections between the PDR relay base and VMD/VMP.</p> <p>Check all connections between the PDR relay base and the “existing” control panel circuitry.</p> <p>If all connections are good, check the voltage between PDR and COM (should be approx 24Vdc). If the voltage is present but the PDR relay contacts are not changing over the PDR relay may be loose in its mounting base or could be faulty. Check that it is correctly inserted in the base. If faulty, replace the PDR relay.</p>	<p>Refer to wiring diagram 9333/729 and schematic 1009238 (1009239 if 2 car entrances)</p> <p>Replacement part no. 901044</p>



